

Quantification of fibre width in biological images

Lake Como School "Computational methods for inverse problems in imaging"

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Introduction

- **Aim** : Enabling a better understanding of microbial ecosystems in order to improve waste-water treatment methods.
- Project based on the analysis of sewage pictures.
- Algorithm associating Canny edge detector-related methods and statistical analysis.

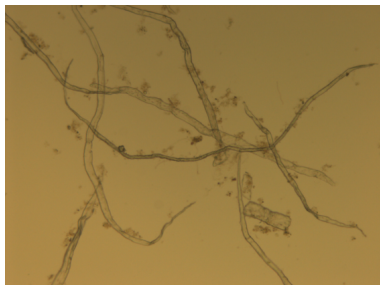


Figure: Raw image u , taken with a fluorescence microscope.

Step 1 : Convolution with Gaussian filters

- Image convolved by two Gaussian filters :

$$\begin{cases} u_1 = K_\sigma * u \\ u_2 = K_{\beta\sigma} * u, \quad \beta < 1 \end{cases}$$

with

$$K_\sigma(k, l) = \frac{1}{2\pi\sigma^2} \exp\left(-\frac{k^2 + l^2}{2\sigma^2}\right)$$

- For example, a $N \times M$ Gaussian filter K_σ applied to the image u provides :

$$u_{1ij} = \sum_{k=0}^{N-1} \sum_{l=0}^{M-1} K_\sigma(k, l) u(i-k, j-l)$$

which can be computed thanks to the Fourier transform :

$$u_1 = \mathcal{F}^{-1}(\mathcal{F}(K_\sigma) \cdot \mathcal{F}(u))$$

Step 2 : Computation of the gradient

- Detection of the edges of an image $f(x, y)$ based on the computation of the gradient.
- The vector :

$$\nabla f(x, y) = \begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{bmatrix} (x, y) = \begin{bmatrix} g_x \\ g_y \end{bmatrix} (x, y)$$

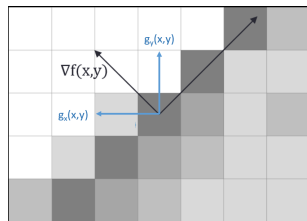
points in the direction of the greater rate of change of f at (x, y) .

- Norm of $\nabla f(x, y)$:

$$\|\nabla f(x, y)\|_2^2 = g_x^2 + g_y^2$$

- Direction of $\nabla f(x, y)$:

$$\theta(x, y) = \arctan\left(\frac{g_y}{g_x}\right)$$



Step 2 : Computation of the gradient

- In our case, the matrix of interest is written, for each pixel :

$$C = \frac{1}{2} \left(\nabla u_1 \nabla u_2^T + \nabla u_2 \nabla u_1^T \right) = \begin{pmatrix} G_{xx} & G_{xy} \\ G_{xy} & G_{yy} \end{pmatrix}$$

where :

$$\begin{cases} G_{xx} = \partial_x u_1 \cdot \partial_x u_2 \\ G_{yy} = \partial_y u_1 \cdot \partial_y u_2 \\ G_{xy} = \frac{1}{2} (\partial_x u_1 \cdot \partial_y u_2 + \partial_y u_1 \cdot \partial_x u_2) \end{cases}$$

- Topological gradient** : largest eigenvalue of C , noted λ_1 .

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- Topological gradient** : largest eigenvalue of C , noted λ_1 .
- Remark* : In the case $u_1 = u_2$:

$$C = \begin{pmatrix} \partial_x u_1^2 & \partial_x u_1 \partial_y u_1 \\ \partial_x u_1 \partial_y u_1 & \partial_y u_1^2 \end{pmatrix} \quad \text{and} \quad \lambda_1 = \partial_x u_1^2 + \partial_y u_1^2 = \|\nabla u_1\|_2^2$$

Step 2 : Computation of the gradient

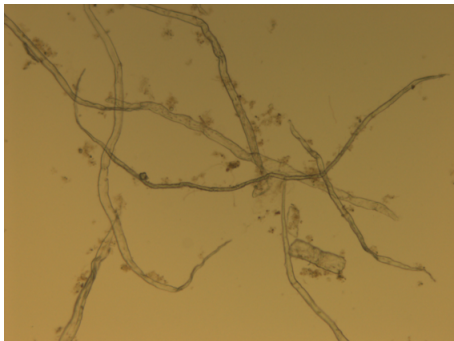


Figure: Raw image u .

Step 2 : Computation of the gradient

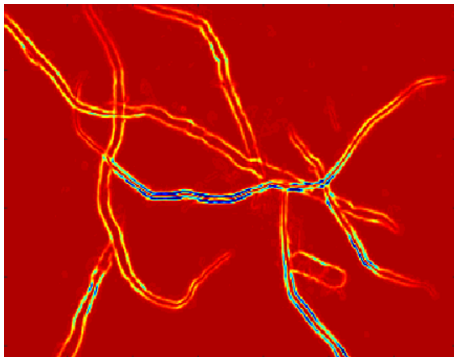
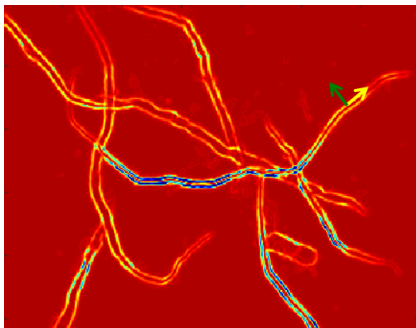
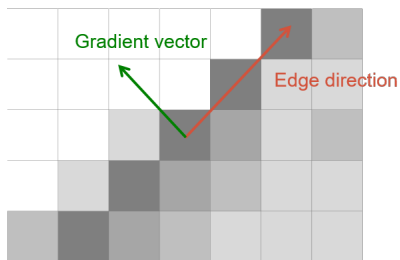


Figure: Topological gradient of u .

Step 3 : Non local maxima suppression

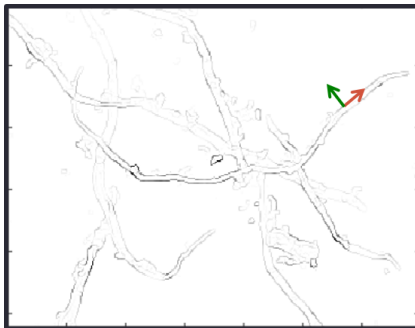
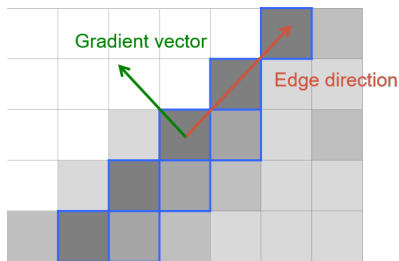
- 1. Find the 2 closest pixels along the edge normal.
- 2. Retain the pixel with maximum magnitude value.



Topological gradient of u .

Step 3 : Non local maxima suppression

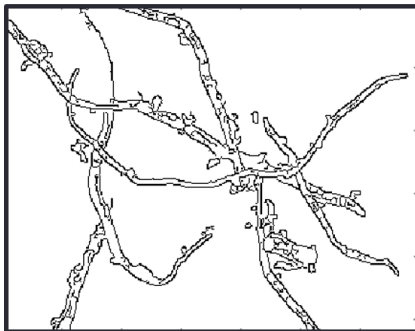
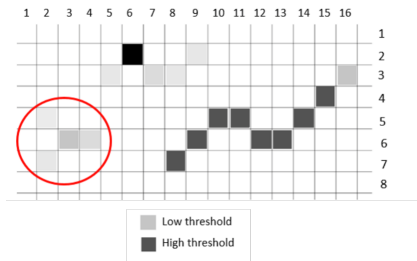
- 1. Find the 2 closest pixels along the edge normal.
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Non local maxima suppression

Step 4 : Hysteresis thresholding

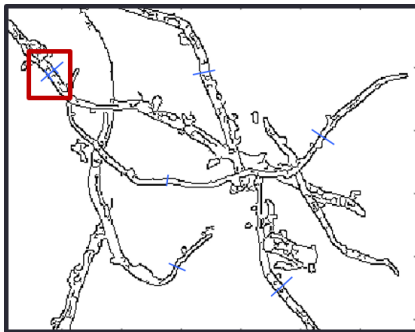
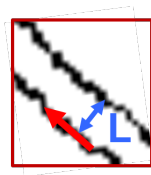
- Keep pixels with a low intensity only if they are connected to a 'strong' pixel.



Binary image after hysteresis thresholding

Step 5 : Computation of fiber width

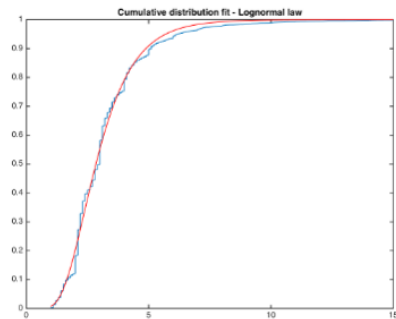
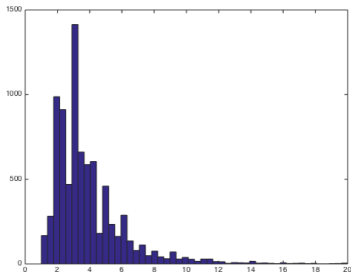
- For each non-zero pixel, the algorithm searches for another edge in the direction of the edge normal.



Binary image after hysteresis thresholding

- Gauss-Newton algorithm for the fitting of the cumulative distribution functions :

$$\min_p \|G(p)\|_{L^2}^2 = \|F_{p_1, \dots, p_K} - F_{data}\|_{L^2}^2$$



Histogram of fiber widths. Abscissa : fiber width (pixels) ; Ordinate : number of fibers by category.

In red : Data cumulative distribution function. In blue : Fitting with lognormal cumulative distribution function.

Comparison of the cumulative distribution functions over several days

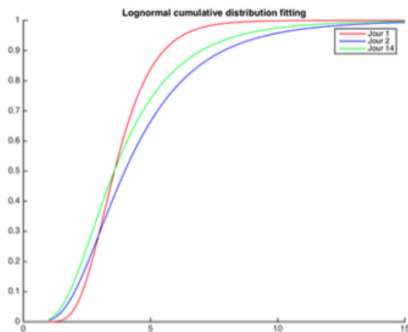





Figure: Lognormal cumulative distribution functions of a sample, for days 1,2 and 14.

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-  Nick Efford.
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