

The Antireflective algebra with applications to image deblurring

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Outline

Signal/Image deblurring

Antireflective Boundary Conditions

The \mathcal{AR} algebra

The spectral decomposition

Regularization by filtering

Numerical results



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The model problem

The restored signal (image) \mathbf{f} is obtained by “solving”:

$$A\mathbf{f} = \mathbf{g}$$

- \mathbf{g} = observed signal = blurred signal + noise
- A = matrix associated to the point spread function (PSF).
- The **PSF** is the observation of one source point, we assume that it is space invariant.



Targets of the restoration

Requirements

- Restored signal of good quality
- Possibility to resort to fast transforms like FFT



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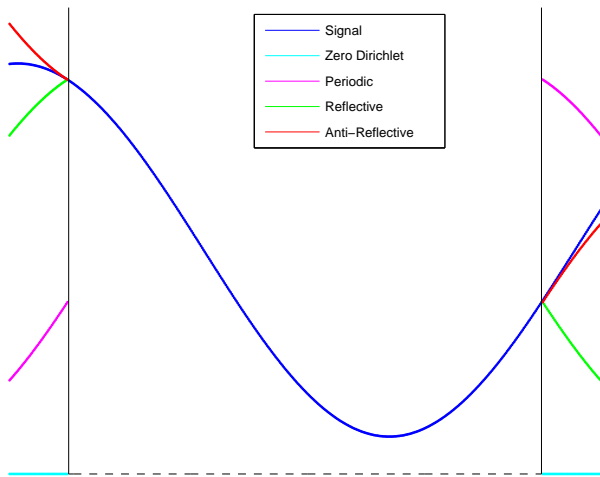
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How to satisfy the requirements

- Problem formalization for the model
- Computational in the definition of the regularization method (multilevel algorithms, regularizing preconditioners, etc.)



Boundary conditions



The coefficient matrix A

The matrix-vector product can be done in $O(n \log n)$ in every case.

Type	Matrix structure	Matrix inversion
Zero Dirichlet	Toeplitz	$O(n^2)$
Periodic	Circulant	$O(n \log n)$ (FFT)
Reflective	Toeplitz + Hankel	generic PSF: $O(n^2)$ symm.: $O(n \log n)$ (DCT-III)
Anti-reflective	Toeplitz + Hankel + rank 2	generic PSF: $O(n^2)$ symm.: $O(n \log n)$ (DST-I + ...)

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Definition of antireflective BCs

- In 1D, the antireflection is obtained by

$$f_{1-j} = 2f_1 - f_{j+1}$$

$$f_{n+j} = 2f_n - f_{n-j}$$

[S. Serra-Capizzano, SIAM J. Sci. Comput. 2003]



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- In the multidimensional case we perform an antireflection with respect to every edge \implies Tensor structure in the multidimensional case.

The reflective BCs assure the continuity at the boundary, while the antireflective BCs assure also the continuity of the first (normal) derivative.



Structural properties

Generic PSF

- $A = \text{Toeplitz} + \text{Hankel} + \text{rank } 2$.
- Matrix vector product in $O(n \log(n))$ ops.



The \mathcal{AR} algebra

With h cosine real-valued polynomial of degree at most $n-3$

$$AR_n(h) = \begin{bmatrix} h(0) & & \\ \mathbf{v}_{n-2}(h) & \tau_{n-2}(h) & J\mathbf{v}_{n-2}(h) \\ & & h(0) \end{bmatrix},$$

where

- J is the flip matrix,
- $\tau_{n-2}(h) = Q \text{diag}_{j=1, \dots, n-2} (h(\frac{j\pi}{n-1})) Q$, with Q the DST-I,
- $\mathbf{v}_{n-2}(h) = \tau_{n-2}(\phi(h)) \mathbf{e}_1$ with $[\phi(h)](x) = \frac{h(x) - h(0)}{2 \cos(x) - 2}$.

$$\mathcal{AR}_n = \{A \in \mathbb{R}^{n \times n} \mid A = AR_n(h)\}$$



Properties of the \mathcal{AR}_n algebra

Computational properties:

- $\alpha AR_n(h_1) + \beta AR_n(h_2) = AR_n(\alpha h_1 + \beta h_2)$,
- $AR_n(h_1)AR_n(h_2) = AR_n(h_1 h_2)$,

Diagonalization

- \mathcal{AR}_n is commutative, since $h = h_1 h_2 \equiv h_2 h_1$,
- the elements of \mathcal{AR}_n are diagonalizable and have a common set of eigenvectors.
- not all matrices in \mathcal{AR}_n are normal.



$AR_n(\cdot)$ Jordan Canonical Form

Theorem

Let h be a cosine real-valued polynomial of degree at most $n-3$. Then

$$AR_n(h) = T_n \text{diag}_{y \in GU\{0\}}(h(y)) T_n^{-1},$$

where $G = \left\{ \frac{j\pi}{n-1} \mid j = 0, \dots, n-2 \right\}$ and

$$T_n = \left(1 - \frac{y}{\pi}, \sin(y), \dots, \sin((n-2)\pi), \frac{y}{\pi} \right) \Big|_{y \in GU\{\pi\}}.$$



Computational issues

- Inverse antireflective transform T_n^{-1} has a structure analogous to T_n .
- The matrix vector product with T_n and T_n^{-1} can be computed in $O(n \log(n))$, but they are not unitary.
- The eigenvalues are mainly obtained by DST-I.
 - $h(0)$ with multiplicity 2
 - DST-I of the first column of $\tau_{n-2}(h)$



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Antireflective BCs and \mathcal{AR} algebra

If the PSF is symmetric, imposing antireflective BCs
the matrix A belongs to \mathcal{AR} .

A possible problem

The \mathcal{AR} algebra is not closed with respect to transposition.



Spectral properties

- Large eigenvalues are associated to lower frequencies.
- $h(0)$ is the largest eigenvalue and the corresponding eigenvector is the sampling of a linear function.
- Hanke et al. in [SISC '08] firstly compute the components of the solution related to the two linear eigenvectors and then regularize the inner part that is diagonalized by DST-I.



Regularization by filtering

- $A = AR_n(h) = T_n D_n T_n^{-1}$

$$T_n = [\mathbf{t}_1 \quad \cdots \quad \mathbf{t}_n], \quad D_n = \text{diag}_{i=1,\dots,n}(d_i), \quad T_n^{-1} = \begin{bmatrix} \tilde{\mathbf{t}}_1^T \\ \vdots \\ \tilde{\mathbf{t}}_n^T \end{bmatrix}$$

with $d_1 = d_n = h(0)$ and $d_i = h\left(\frac{(i-1)\pi}{n-1}\right)$, for $i = 2, \dots, n-2$,

- A **spectral filter solution** is given by

$$\mathbf{f}_{\text{reg}} = \sum_{i=1}^n \phi_i \frac{\tilde{\mathbf{t}}_i^T \mathbf{g}}{d_i} \mathbf{t}_i, \quad (1)$$

where \mathbf{g} is the observed image and ϕ_i are the filter factors.



Filter factors

- Truncated spectral value decomposition (TSVD)

$$\phi_i^{\text{tsvd}} = \begin{cases} 1 & \text{if } d_i \geq \delta \\ 0 & \text{if } d_i < \delta \end{cases}$$

- Tikhonov regularization

$$\phi_i^{\text{tik}} = \frac{d_i^2}{d_i^2 + \lambda}, \quad \lambda > 0,$$

- Imposing $\phi_1 = \phi_n = 1$, the solution \mathbf{f}_{reg} is exactly that obtained by the homogeneous antireflective BCs in [Hanke et al. SISC '08].



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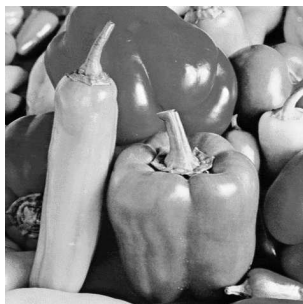
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Tikhonov regularization

- Gaussian blur
- 1% of white Gaussian noise



True image



Observed image

Restored images.



Reflective



Antireflective

Best restoration errors

Relative restoration error defined as $\|\hat{\mathbf{f}} - \mathbf{f}\|_2 / \|\mathbf{f}\|_2$,
 where $\hat{\mathbf{f}}$ is the computed approximation of the true image \mathbf{f} .

noise	Reflective	Anti-Reflective
10%	0.1284	0.1261
1%	0.1188	0.1034
0.1%	0.1186	0.0989



Conclusions

- The AR-BCs have the same computationally properties of the R-BCs but lead to better restorations.
- The importance of to have good BCs increases when the PSF has a large support and the noise is not huge.
- The spectral decomposition of AR matrices could be useful for other regularization methods?
- At my home-page:

<http://scienze-como.uninsubria.it/mdonatelli/>

Preprints, software, slides, ...

